

# Covariance Operator Estimation in the Small Lengthscale Regime

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## Joint work with



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# Outline

Covariance Matrix Estimation

Covariance Operator Estimation

Application in Ensemble Kalman Filters

Summary

# Covariance Matrix Estimation

**Model:** Let  $X_1, X_2, \dots, X_N \in \mathbb{R}^p$  be i.i.d.  $\mathcal{N}(0, \Sigma)$

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$$\mathbb{E} \|\tilde{\Sigma} - \Sigma\| \asymp \|\Sigma\| \left( \sqrt{\frac{r(\Sigma)}{N}} \vee \frac{r(\Sigma)}{N} \right), \quad r(\Sigma) := \frac{\text{Tr}(\Sigma)}{\|\Sigma\|} \text{ (effective rank)}$$

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**Example:**  $\Sigma = I_{p \times p}$ ,  $\text{Tr}(\Sigma) = p$ ,  $\|\Sigma\| = 1$

$$\mathbb{E} \|\tilde{\Sigma} - I_{p \times p}\| \asymp \sqrt{\frac{p}{N}} \vee \frac{p}{N}$$

**Sample complexity:**  $N = \mathcal{O}(p)$



# Covariance Matrix Estimation

## Question:

- ▶ In high-dimensional setting,  $p \gg N$ .
- ▶ Can we do better under some structured assumption on  $\Sigma$  ?

# Sparse Covariance [Bickel and Levina, 2008]

Parameter space: row-wise  $\ell_q$ -“norm” sparsity

$$\mathcal{U}(q, s, M) = \left\{ \Sigma : \max_{1 \leq i \leq p} \sigma_{ii} \leq M, \max_{1 \leq i \leq p} \sum_{j=1}^p |\sigma_{ij}|^q \leq s \right\}, \quad 0 \leq q < 1$$

Thresholded estimator:  $\hat{\Sigma} = (\hat{\sigma}_{ij})_{p \times p}$

$$\hat{\sigma}_{ij} = \tilde{\sigma}_{ij} \mathbf{1}\{|\tilde{\sigma}_{ij}| \geq \lambda\}, \quad \text{with} \quad \lambda = C \sqrt{\frac{\log p}{N}}$$

Covergence Rate:

$$\|\hat{\Sigma} - \Sigma\| = O_P \left( s \left( \frac{\log p}{N} \right)^{\frac{1-q}{2}} \right)$$

Sample complexity:  $N = \mathcal{O}(\log p)$

## Brief summary

- ▶ General  $\Sigma$ :  $N \sim p$
- ▶ Sparse  $\Sigma$ :  $N \sim \log(p)$  (thresholded estimator)
- ▶ Other structured covariance matrices:  
Bandable, Toeplitz, Spiked sparse... [Cai et al., 2016]
- ▶ Minimax optimality: [Cai et al., 2010, Cai and Zhou, 2012]
- ▶ One of the central subjects in **high-dimensional statistics**  
[Wainwright, 2019]

# Covariance Operator Estimation

# Covariance Operator Estimation

**Model:** Let  $u_1, u_2, \dots, u_N$  be i.i.d. centered and continuous Gaussian random **functions** on  $D = [0, 1]^d$

**Covariance function:**  $k(x, x') = \mathbb{E}[u(x)u(x')]$ ,  $x, x' \in D$

**Covariance operator:**  $\mathcal{C} : L^2(D) \rightarrow L^2(D)$

$$(\mathcal{C}\psi)(\cdot) = \int_D k(\cdot, x')\psi(x') dx', \quad \psi \in L^2(D)$$

**Goal:** Estimate  $\mathcal{C}$  under the operator norm

# Covariance Operator Estimation

Sample covariance function:

$$\hat{k}(x, x') = \frac{1}{N} \sum_{n=1}^N u_n(x) u_n(x')$$

Sample covariance operator:  $\hat{\mathcal{C}} : L^2(D) \rightarrow L^2(D)$

$$(\hat{\mathcal{C}}\psi)(\cdot) = \int_D \hat{k}(\cdot, x') \psi(x') dx', \quad \psi \in L^2(D)$$

Nonasymptotic Rate: [Koltchinskii and Lounici, 2017]

$$\mathbb{E} \|\tilde{\Sigma} - \Sigma\| \asymp \|\Sigma\| \left( \sqrt{\frac{r(\Sigma)}{N}} \vee \frac{r(\Sigma)}{N} \right), \quad r(\Sigma) := \frac{\text{Tr}(\Sigma)}{\|\Sigma\|}$$

**Question:** Can we design better estimators under some structured assumption, e.g. sparsity?

# Thresholded estimator

Sparse class: row-wise  $\ell_q$ -“norm” sparsity

$$\sup_{x \in D} \left( \int_D |k(x, x')|^q dx' \right)^{\frac{1}{q}} \leq R_q, \quad q \in (0, 1)$$

(similar to matrix sparsity assumption:  $\max_i \sum_{j=1}^p |\sigma_{ij}|^q \leq s$ )

Thresholded covariance function:

$$\widehat{k}_{\rho_N}(x, x') := \widehat{k}(x, x') \mathbf{1}_{\{|\widehat{k}(x, x')| \geq \rho_N\}}(x, x'), \quad \rho_N : \text{thresholding level}$$

Thresholded covariance operator:

$$(\widehat{\mathcal{C}}_{\rho_N} \psi)(\cdot) := \int_D \widehat{k}_{\rho_N}(\cdot, x') \psi(x') dx', \quad \psi \in L^2(D)$$

# Main Results



# Main result 1

## Assumption

(i) *Normalization*:  $\sup_{x \in D} \mathbb{E}[u(x)^2] = 1$

(ii) *Sparsity*:  $\sup_{x \in D} \left( \int_D |k(x, x')|^q dx' \right)^{\frac{1}{q}} \leq R_q, \quad q \in (0, 1)$

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## Theorem (Al-Ghattas, C., Sanz-Alonso, Waniorek)

Assume  $N \gtrsim (\mathbb{E}[\sup_{x \in D} u(x)])^2$ , set

$$\rho_N \asymp \frac{1}{\sqrt{N}} \mathbb{E} \left[ \sup_{x \in D} u(x) \right],$$
$$\hat{\rho}_N \asymp \frac{1}{\sqrt{N}} \left( \frac{1}{N} \sum_{n=1}^N \sup_{x \in D} u_n(x) \right).$$

Then,

$$\mathbb{E} \|\hat{\mathcal{C}}_{\hat{\rho}_N} - \mathcal{C}\| \lesssim R_q^q \rho_N^{1-q}.$$

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**Proof:** Careful analysis of thresholded estimator, concentration of  $\hat{\rho}_N$ , tail bounds in covariance function estimation (product and multiplier empirical process results [Mendelson, 2016]), etc.

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## Assumption

- (i)  $k(x, x') = k(|x - x'|) > 0$ ,  $k(r)$  is differentiable, strictly decreasing on  $[0, \infty)$ , and satisfies  $k(r) \rightarrow 0$  as  $r \rightarrow \infty$ .
- (ii)  $k = k_\lambda$  depends on a *correlation lengthscale parameter*  $\lambda > 0$  such that  $k_\lambda(\alpha r) = k_{\lambda\alpha^{-1}}(r)$  for any  $\alpha > 0$ , and  $k_\lambda(0) = k(0)$  is independent of  $\lambda$ .

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## Two popular examples:

Squared Exponential:  $k_\lambda^{\text{SE}}(x, x') = \exp\left(-\frac{|x-x'|^2}{2\lambda^2}\right)$

Matérn:  $k_\lambda^{\text{Ma}}(x, x') = \frac{2^{1-\nu}}{\Gamma(\nu)} \left(\frac{\sqrt{2\nu}}{\lambda}|x - x'|\right)^\nu K_\nu\left(\frac{\sqrt{2\nu}}{\lambda}|x - x'|\right)$

[Stein, 1999] [Williams and Rasmussen, 2006]...

## Main result 2

### Theorem (Small lengthscale regime)

Assume  $N \gtrsim \log(\lambda^{-d})$ , set

$$\hat{\rho}_N \asymp \frac{1}{\sqrt{N}} \left( \frac{1}{N} \sum_{n=1}^N \sup_{x \in D} u_n(x) \right).$$

Then, for sufficiently small  $\lambda$ ,

$$\frac{\mathbb{E} \|\hat{\mathcal{C}} - \mathcal{C}\|}{\|\mathcal{C}\|} \asymp \sqrt{\frac{\lambda^{-d}}{N}} \vee \frac{\lambda^{-d}}{N},$$
$$\frac{\mathbb{E} \|\hat{\mathcal{C}}_{\hat{\rho}_N} - \mathcal{C}\|}{\|\mathcal{C}\|} \leq c(d, q) \left( \frac{\log(\lambda^{-d})}{N} \right)^{\frac{1-q}{2}},$$

where  $c(d, q) \asymp (\int_0^\infty k_1(r)^q r^{d-1} dr) / (\int_0^\infty k_1(r) r^{d-1} dr)$ .

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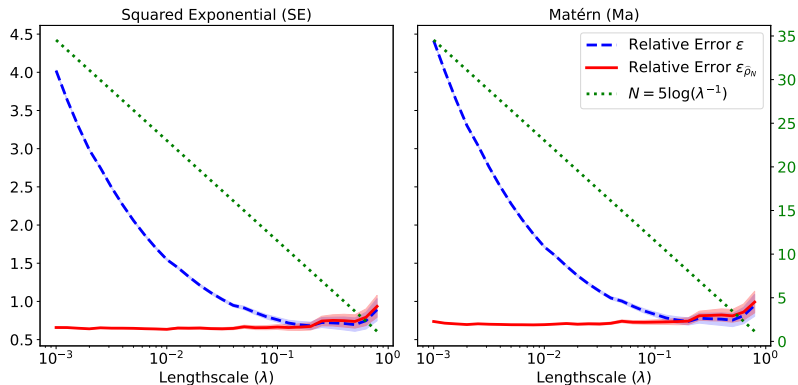
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where  $c(d, q) \asymp (\int_0^\infty k_1(r)^q r^{d-1} dr) / (\int_0^\infty k_1(r) r^{d-1} dr)$ .

**Proof:**  $R_q \asymp \lambda^d \int_0^\infty k_1(r)^q r^{d-1} dr$ ,  $\|\mathcal{C}\| \asymp \lambda^d \int_0^\infty k_1(r) r^{d-1} dr$ , and

$\mathbb{E}[\sup_{x \in D} u(x)] \asymp \sqrt{\log(\lambda^{-d})}$ .

# A simple numerical experiment



**Figure 1:** Plots of the average relative error and 95% confidence intervals achieved by the sample ( $\varepsilon$ , dashed blue) and thresholded ( $\varepsilon_{\hat{\rho}_N}$ , solid red) covariance estimators based on sample size ( $N$ , dotted green) for the squared exponential kernel (left) and Matérn kernel (right) over 100 trials.

# Application in EnKFs

# Application in Ensemble Kalman Filters

Linear forward model:

$$y = \mathcal{A}u + \eta, \quad u \in L^2(D), \quad y \in \mathbb{R}^{d_y}, \quad \eta \sim \mathcal{N}(0, \Gamma)$$

Ensemble Kalman filters (EnKFs):

$$\{u_n\}_{n=1}^N \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(0, \mathcal{C}), \quad y \implies \{v_n\}_{n=1}^N$$

*Perturbed observation or stochastic EnKF [Evensen, 1994]:*

$$v_n := u_n + \mathcal{K}(\widehat{\mathcal{C}})(y - \mathcal{A}u_n - \eta_n), \quad 1 \leq n \leq N$$

*Kalman gain*  $\mathcal{K}(\mathcal{C}) := \mathcal{C}\mathcal{A}^* (\mathcal{A}\mathcal{C}\mathcal{A}^* + \Gamma)^{-1}$ ,  $\{\eta_n\}_{n=1}^N \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(0, \Gamma)$ .

*Mean-field EnKF:*

$$v_n^* := u_n + \mathcal{K}(\mathcal{C})(y - \mathcal{A}u_n - \eta_n), \quad 1 \leq n \leq N$$

Use thresholded covariance:

$$v_n^\rho := u_n + \mathcal{K}(\widehat{\mathcal{C}}_{\rho_N})(y - \mathcal{A}u_n - \eta_n), \quad 1 \leq n \leq N$$

# Application in Ensemble Kalman Filters

## Theorem (Approximation of Mean-Field EnKF)

Set

$$\rho_N \asymp \frac{1}{\sqrt{N}} \left( \frac{1}{N} \sum_{n=1}^N \sup_{x \in D} u_n(x) \right).$$

Then,

$$\begin{aligned} \mathbb{E} [|v_n - v_n^*| \mid u_n, \eta_n] &\lesssim c \left[ c(d) \left( \sqrt{\frac{\lambda^{-d}}{N}} \vee \frac{\lambda^{-d}}{N} \right) \right], \\ \mathbb{E} [|v_n^\rho - v_n^*| \mid u_n, \eta_n] &\lesssim c \left[ c(d, q) \left( \frac{\log(\lambda^{-d})}{N} \right)^{\frac{1-q}{2}} \right], \end{aligned}$$

where  $c = \|\mathcal{A}\| \|\Gamma^{-1}\| \|C\| |y - \mathcal{A}u_n - \eta_n|$ .

# Summary

# Takeaways

Covariance matrix estimation:  $\mathcal{N}(0, \Sigma_{p \times p})$

- ▶ General  $\Sigma$ :  $N \sim p$
- ▶ Sparse  $\Sigma$ :  $N \sim \log(p)$

thresholded estimator, minimax optimal

Covariance operator estimation:  $\mathcal{N}(0, \mathcal{C})$

- ▶  $\lambda$ : lengthscale     $d$ : ambient dimension
- ▶ General  $\mathcal{C}$ :  $N \sim \lambda^{-d}$
- ▶ Sparse  $\mathcal{C}$ :  $N \sim \log(\lambda^{-d})$     thresholded estimator

Many applications: EnKFs, etc.

## Future directions

- ▶ Other structured covariance operators & minimax optimal rates
- ▶ Nonstationary fields, heavy tailed distribution, robustness
- ▶ Operator learning, learning Green's functions, GPs, etc
- ▶ Fast solvers: Hierarchical matrices, low-rank approximation, etc
- ▶ Precision matrix/operator estimation, learning Gaussian graphical models, etc



Thanks!

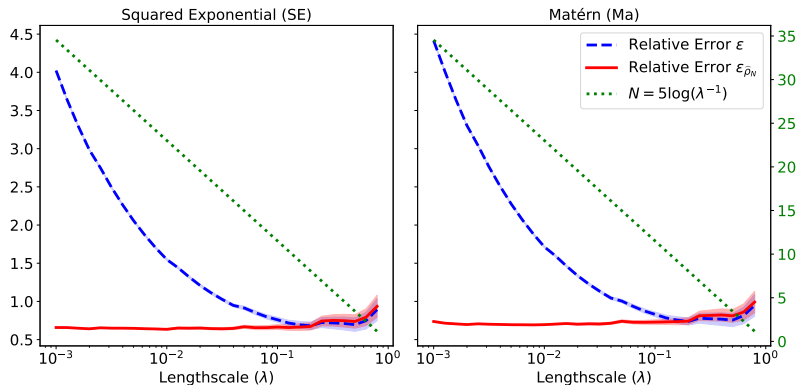
# Experiment details

Squared Exponential:  $k_{\lambda}^{\text{SE}}(x, x') = \exp\left(-\frac{|x-x'|^2}{2\lambda^2}\right)$

Matérn:  $k_{\lambda, \nu}^{\text{Ma}}(x, x') = \frac{2^{1-\nu}}{\Gamma(\nu)} \left(\frac{\sqrt{2\nu}}{\lambda}|x-x'|\right)^{\nu} K_{\nu}\left(\frac{\sqrt{2\nu}}{\lambda}|x-x'|\right)$

- ▶ Uniformly discretize  $D = [0, 1]$  using a mesh of  $L = 1250$  points
- ▶  $\mathcal{C}^{ij} = k(x_i, x_j), \quad 1 \leq i, j \leq L$
- ▶  $\hat{\mathcal{C}}^{ij} = \frac{1}{N} \sum_{n=1}^N u_n(x_i) u_n(x_j), \quad \hat{\mathcal{C}}_{\hat{\rho}_N}^{ij} = \hat{\mathcal{C}}^{ij} \mathbf{1}_{\{\hat{\mathcal{C}}^{ij} \geq \hat{\rho}_N\}}, \quad 1 \leq i, j \leq L$
- ▶  $\varepsilon = \frac{\|\mathcal{C} - \hat{\mathcal{C}}\|}{\|\mathcal{C}\|}, \quad \varepsilon_{\hat{\rho}_N} = \frac{\|\mathcal{C} - \hat{\mathcal{C}}_{\hat{\rho}_N}\|}{\|\mathcal{C}\|}$
- ▶ 30 lengthscales arranged uniformly in log-space  
(range from  $10^{-3}$  to  $10^{-0.1}$ )
- ▶  $N = 5 \log(1/\lambda)$

# A simple numerical experiment



**Figure 2:** Plots of the average relative error and 95% confidence intervals achieved by the sample ( $\varepsilon$ , dashed blue) and thresholded ( $\varepsilon_{\hat{\rho}_N}$ , solid red) covariance estimators based on sample size ( $N$ , dotted green) for the squared exponential kernel (left) and Matérn kernel (right) over 100 trials.



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